

Homework

1. Show that the zero of vector addition is unique.

Proof: If there are two zero 0 and O , since 0 is a zero, we have

$$O=0+O \tag{1}$$

Moreover, since O is also zero, we have

$$0=0+O \tag{2}$$

From (1) and (2), we obtain $O=0+O=0$.

2. Show the axiom $0x = 0$ by using other seven axioms in the definition of linear space.

Proof: For arbitrary x in the set X , we have

$$x+0x=(1+0)x=1x=x. \tag{3}$$

Adding the negative of x on the both side of (3), $x+(-x)+0x=x+(-x)=0$. Thus $0x=0$.

3. Suppose that the set X is the set of positive real numbers (i.e. $x > 0$), if the addition and scalar multiplication with the field R of real numbers are defined as follows

$$x + y = xy, \quad cx = x^c,$$

Show this set under this addition and scalar multiplication is a linear space.

Proof:

First, we prove the closeness of addition and scalar multiplication. For any $x, y, z \in X$

and $c \in R$, then $x > 0, y > 0, z > 0$, Thus we have

$$x + y = xy > 0 \quad \text{and} \quad cx = x^c > 0. \text{ The closeness is proved.}$$

Next, we prove the following results.

1. $x + y = xy = yx = y + x$
2. $(x + y) + z = xy + z = xyz = x + yz = x + (y + z)$
3. $x + 1 = x1 = x$, so 1 is the zero element.
4. $x + 1/x = x(1/x) = 1$, so $1/x$ is the negative element of x .

For any $k, h \in R$, we have

5. $k(hx) = kx^h = x^{kh} = (kh)x$
6. $k(x + y) = k(xy) = (xy)^k = x^k y^k = kx + ky$
7. $(k + h)x = x^{k+h} = x^k x^h = kx + hx$

8. $1x = x^1 = x$ Therefore, set X with the field \mathbb{R} of real numbers is a linear space.

4. Suppose that the set X is 2-dimensional vector set of real numbers \mathbb{R}^2 with the following addition and scalar multiplication with the field \mathbb{R} of real numbers

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 + x_1 x_2 \end{bmatrix}$$

$$k \cdot \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} kx_1 \\ ky_1 + \frac{k(k-1)}{2} x_1^2 \end{bmatrix}$$

Show this set under this addition and scalar multiplication is a linear space.

证明：首先我们证明该集合关于加法和数乘运算的封闭性。对任意 $\begin{bmatrix} x_1 \\ y_1 \end{bmatrix}, \begin{bmatrix} x_2 \\ y_2 \end{bmatrix}, \begin{bmatrix} x_3 \\ y_3 \end{bmatrix} \in X$ 和

$k \in \mathbb{R}$ ，我们可以得到

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 + x_1 x_2 \end{bmatrix} \in X$$

$$k \cdot \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} kx_1 \\ ky_1 + \frac{k(k-1)}{2} x_1^2 \end{bmatrix} \in X$$

因而，该集合关于加法和数乘运算是封闭的。接下来，我们证明线性空间的另外 8 条。

$$1. \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 + x_1 x_2 \end{bmatrix}, \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \oplus \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} x_2 + x_1 \\ y_2 + y_1 + x_2 x_1 \end{bmatrix}$$

因而， $\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \oplus \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$ ，交换律成立。

$$2. \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \left(\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \oplus \begin{bmatrix} x_3 \\ y_3 \end{bmatrix} \right) = \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} x_2 + x_3 \\ y_2 + y_3 + x_2 x_3 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 + x_3 \\ y_1 + y_2 + y_3 + x_2 x_3 + x_1 x_2 + x_1 x_3 \end{bmatrix}$$

$$\left(\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \right) \oplus \begin{bmatrix} x_3 \\ y_3 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ y_1 + y_2 + x_1 x_2 \end{bmatrix} \oplus \begin{bmatrix} x_3 \\ y_3 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 + x_3 \\ y_1 + y_2 + y_3 + x_1 x_2 + x_1 x_3 + x_2 x_3 \end{bmatrix}$$

因而， $\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \left(\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \oplus \begin{bmatrix} x_3 \\ y_3 \end{bmatrix} \right) = \left(\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} x_2 \\ y_2 \end{bmatrix} \right) \oplus \begin{bmatrix} x_3 \\ y_3 \end{bmatrix}$

$$3. \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} x_1 + 0 \\ y_1 + 0 + 0 \end{bmatrix} = \begin{bmatrix} x_1 \\ y_1 \end{bmatrix}, \text{ 所以 } \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ 是该线性空间的零元。}$$

$$4. \begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \oplus \begin{bmatrix} -x_1 \\ -y_1 + x_1^2 \end{bmatrix} = \begin{bmatrix} x_1 + (-x_1) \\ y_1 + (-y_1 + x_1^2) + x_1(-x_1) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \text{ 所以}$$

该线性空间中 $\begin{bmatrix} x_1 \\ y_1 \end{bmatrix}$ 的负元为 $\begin{bmatrix} -x_1 \\ -y_1 + x_1^2 \end{bmatrix}$ 。

对任意的数域 \mathbb{R} 中的数 $k, h \in \mathbb{R}$, 我们有

$$5. k \left(h \left(\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \right) \right) = k \left(\begin{bmatrix} hx_1 \\ hy_1 + \frac{h(h-1)}{2} x_1^2 \end{bmatrix} \right) = \begin{bmatrix} khx_1 \\ k \left(hy_1 + \frac{h(h-1)}{2} x_1^2 \right) + \frac{k(k-1)}{2} (hx_1)^2 \end{bmatrix}$$

$$(kh) \left(\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \right) = \begin{bmatrix} khx_1 \\ khy_1 + \frac{kh(kh-1)}{2} x_1^2 \end{bmatrix} = \begin{bmatrix} khx_1 \\ k \left(hy_1 + \frac{h(h-1)}{2} x_1^2 \right) + \frac{k(k-1)}{2} (hx_1)^2 \end{bmatrix}$$

$$\text{所以 } k \left(h \left(\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \right) \right) = (kh) \left(\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} \right)$$

$$\begin{aligned} \textcircled{6} k(X+Y) &= k[x_1+x_2 \quad y_1+y_2+x_1x_2]^T \\ &= [k(x_1+x_2) \quad k(y_1+y_2+x_1x_2) + k(k-1)(x_1+x_2)^2/2]^T \\ &= [k(x_1+x_2) \quad k(y_1+y_2) + k^2(x_1+x_2)^2/2 - k(x_1^2+x_2^2)/2]^T \\ kX+kY &= [kx_1 \quad ky_1+k(k-1)x_1^2/2]^{-1} + [kx_2 \quad ky_2+k(k-1)x_2^2/2]^T \\ &= [k(x_1+x_2) \quad k(y_1+y_2) + k^2(x_1+x_2)^2/2 - k(x_1^2+x_2^2)/2]^T \\ \therefore k(X+Y) &= kX+kY \\ (k+h)X &= [(k+h)x_1 \quad (k+h)y_1 + (k+h)(k+h-1)x_1^2/2]^T \\ &= [(k+h)x_1 \quad (k+h)y_1 + (k+h)^2x_1^2/2 - (k+h)x_1^2/2]^T \\ kX+hX &= [kx_1 \quad ky_1+k(k-1)x_1^2/2]^{-1} + [hx_1 \quad hy_1+h(h-1)x_1^2/2]^T \\ &= [(k+h)x_1 \quad (k+h)y_1 + (k+h)^2x_1^2/2 - (k+h)x_1^2/2]^T \\ \therefore (k+h)X &= kX+hX \\ \textcircled{7} 1X &= [1x_1 \quad 1y_1+1(1-1)x_1^2/2]^T \\ &= [x_1 \quad y_1]^T \\ &= X \end{aligned}$$

Homework

1. Show that R^n and P^{n-1} over the same field R (the field of real numbers) are isomorphic.

Proof: Let e_1, e_2, \dots, e_n be a basis of R^n and v_1, v_2, \dots, v_n be a basis of P^{n-1} . Generally,

$$e_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}, \dots, e_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

$$v_1 = 1, v_2 = t, \dots, v_n = t^{n-1}.$$

Then, for any $x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in R^n$ and $\lambda \in R$, we have $x = x_1 e_1 + x_2 e_2 + \dots + x_n e_n$ and

$$p(t) = a_0 v_1 + a_1 v_2 + \dots + a_{n-1} v_n.$$

Define a mapping from R^n to P^{n-1} as following,

$$T(x) = x_1 + x_2 t + \dots + x_n t^{n-1}$$

Next, we prove that this mapping is onto and one to one.

Onto: For any $p(t) = a_0 v_1 + a_1 v_2 + \dots + a_{n-1} v_n \in P^{n-1}$, there exists a such that $T(a) = p(t)$

One to one: for any $x, y \in R^n$, if $T(x) = T(y)$, that is,

$$x_1 + x_2 t + \dots + x_n t^{n-1} = y_1 + y_2 t + \dots + y_n t^{n-1}$$

$$(x_1 - y_1) + (x_2 - y_2)t + \dots + (x_n - y_n)t^{n-1} = 0$$

Since $v_1 = 1, v_2 = t, \dots, v_n = t^{n-1}$ are linearly independent, we have $x = y$

Therefore we find the isomorphic mapping between R^n and P^{n-1} .

2. Show that each finite-dimensional linear space X over field K is isomorphic to K^n , $n = \dim X$. Show that this isomorphism is not unique.

Proof:

We assume that the dimension of linear space X is n . There exists a basis v_1, v_2, \dots, v_n .

Then, for any element $x \in X$, $x = x_1v_1 + x_2v_2 + \dots + x_nv_n$, $x_1, x_2, \dots, x_n \in K$

Define a mapping from X to K^n as following

$$T(x) = (x_1, x_2, \dots, x_n),$$

Next, we show that this mapping is isomorphic.

Onto: For any $(x_1, x_2, \dots, x_n) \in K^n$, there exists $x = x_1v_1 + x_2v_2 + \dots + x_nv_n \in X$ such that

$$T(x) = (x_1, x_2, \dots, x_n) .$$

One to one: for any $x, y \in X$, where $y = y_1v_1 + y_2v_2 + \dots + y_nv_n$, if $T(x) = T(y)$, that is,

$$(x_1, x_2, \dots, x_n) = (y_1, y_2, \dots, y_n)$$

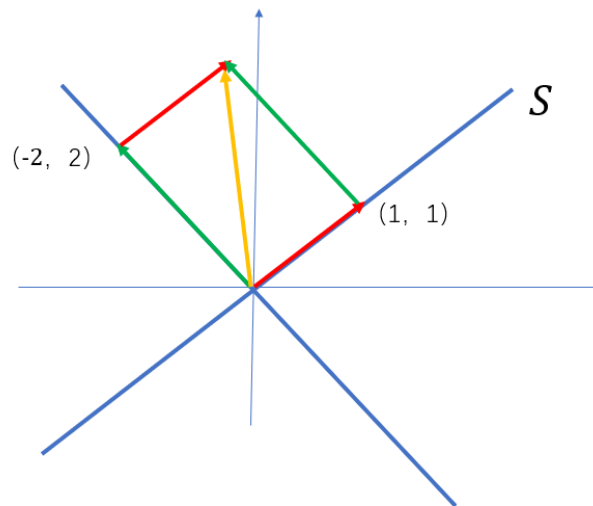
That means $x_i = y_i$, thus $x = y$

Homework

1. Please determine whether the following set is a subspace of \mathbb{R}^2 . If yes, please show it. If no, please explain the reason.

$$S = \left\{ \begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix} \in \mathbb{R}^2 \mid \omega_1^2 = \omega_2^2 \right\}$$

Answer: It is not a subspace. $\omega_1^2 = \omega_2^2$ means $\omega_1 = \omega_2$ or $\omega_1 = -\omega_2$, which are two lines in the \mathbb{R}^2 described as the following figure,



$(-2,2)+(1,1)=(-1,3)$, $(-1,3)$ is not in the set S . Thus the set S is not closed under the addition. Therefore it is not a subspace.

2. Please show that the subset $X = \{f(t) : \mathbb{R} \rightarrow \mathbb{R} \mid f(t) = f(-t)\}$ of even functions is a subspace of real-valued functions.

Proof: For any $f(t), g(t) \in X$ and $k \in \mathbb{R}$, we have

$$(f + g)(t) = f(t) + g(t) = f(-t) + g(-t) = (f + g)(-t)$$

$$(kf)(t) = kf(t) = kf(-t) = (kf)(-t)$$

These show that the set X are closed the addition and scalar multiplication. Thus it is a subspace of real-valued functions.

Homework

1. Please determine whether the following vectors are linear independent?

$$(1) \quad a_1 = (2, -1, 0, 3), \quad a_2 = (1, 2, 5, -1), \quad a_3 = (7, -1, 5, 8)$$

$$(2) \quad p_1(x) = 1 - x, \quad p_2(x) = 5 + 3x - 2x^2, \quad p_3(x) = 1 + 3x - 2x^2$$

Answer:

(1) We consider the coefficients c_1, c_2, c_3 such that

$$c_1 a_1 + c_2 a_2 + c_3 a_3 = 0 \quad (1)$$

Putting a_1, a_2, a_3 into equation (1), we have

$$\begin{aligned} 2c_1 + c_2 + 7c_3 &= 0 \\ -c_1 + 2c_2 - c_3 &= 0 \\ 5c_2 + 5c_3 &= 0 \\ 3c_1 - c_2 + 8c_3 &= 0 \end{aligned} \quad \begin{bmatrix} 2 & 1 & 7 \\ -1 & 2 & -1 \\ 0 & 5 & 5 \\ 3 & -1 & 8 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad (2)$$

The reduced Row Echelon Form (RREF) of coefficient matrix is

$$\begin{bmatrix} 1 & 0 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

That is, $c_1 = -3c_3, c_2 = -c_3$, $\begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = c_3 \begin{bmatrix} -3 \\ -1 \\ 1 \end{bmatrix}$. Thus the system (2) of linear equations

has nonzero solution

(3) We consider the coefficients c_1, c_2, c_3 such that

$$c_1 p_1(x) + c_2 p_2(x) + c_3 p_3(x) = 0 \quad (3)$$

Putting $p_1(x), p_2(x), p_3(x)$ into equation (3), we have

$$c_1(1-x) + c_2(5+3x-2x^2) + c_3(1+3x-2x^2) = 0$$

Arranging this equation, we obtain

$$(c_1 + 5c_2 + c_3) + (-c_1 + 3c_2 + 3c_3)x + (-2c_2 - 2c_3)x^2 = 0$$

Thus

$$\begin{bmatrix} 1 & 5 & 1 \\ -1 & 3 & 3 \\ 0 & -2 & -2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The reduced Row Echelon Form (RREF) of coefficient matrix is

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

This means that $c_1 = c_2 = c_3 = 0$. Therefore $p_1(x), p_2(x), p_3(x)$ are linearly independent.

2. Let V be a vector space over \mathbb{R} and $n \in \mathbb{N}$ be an odd number. If the vectors $x_1, x_2, \dots, x_n \in V$ are linearly independent, then the same stands also for the vectors $x_1 + x_2, x_2 + x_3, \dots, x_{n-1} + x_n, x_n + x_1$.

Answer: First, we find the coefficients c_1, c_2, \dots, c_n such that

$$c_1(x_1 + x_2) + c_2(x_2 + x_3) + \dots + c_{n-1}(x_{n-1} + x_n) + c_n(x_n + x_1) = 0$$

Arranging this equation, we obtain

$$(c_1 + c_n)x_1 + (c_1 + c_2)x_2 + \dots + (c_{n-1} + c_n)x_n = 0$$

From the linear independence of x_1, x_2, \dots, x_n , we have

$$c_1 + c_n = 0, c_1 + c_2 = 0, \dots, c_{n-1} + c_n = 0$$

Since n is an odd number, $(c_1 + c_n) - (c_1 + c_2) + (c_2 + c_3) - \dots + (c_{n-1} + c_n) = 2c_n = 0$. From

$$c_n = 0, \text{ we can obtain } c_1 = c_2 = \dots = c_{n-1} = 0$$

Homework

1. Let $P^{n \times n}$ be a set of all $n \times n$ matrices,

(1) Please show that the set of all the matrices that are exchangeable with $A \in P^{n \times n}$ is a subspace of $P^{n \times n}$. If this subspace is denoted as $C(A)$. It means

$$C(A) = \{B \in P^{n \times n} \mid AB = BA, A \in P^{n \times n}\}.$$

(2) When $A = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & \cdots & 1 \end{bmatrix}$, please find $C(A)$.

(3) If $A = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 2 & \cdots & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & \cdots & n \end{bmatrix}$, please find the dimension and a basis of $C(A)$.

Answer:

(1) For any $B, D \in C(A)$ and $k \in R$, we have

$$A(B + D) = AB + AD = BA + DA = (B + D)A$$

$$A(kB) = kAB = kBA = (kB)A$$

Thus the addition and scalar multiplication are closed. The subset is a subspace of $P^{n \times n}$.

(2) When $A = I$, since for any matrix $B \in P^{n \times n}$, we have $BI = B = IB$. Thus

$$C(A) = P^{n \times n}.$$

(3) When $A = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 2 & \cdots & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & \cdots & n \end{bmatrix}$, we assume $B = \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{nn} \end{bmatrix}$. Putting A into

$AB = BA$, the left side of equation is

$$\begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 2 & \cdots & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & \cdots & n \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{nn} \end{bmatrix} = \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ 2b_{21} & 2b_{22} & \cdots & 2b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ nb_{n1} & nb_{n2} & \cdots & nb_{nn} \end{bmatrix}$$

and the right side of equation is

$$\begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{nn} \end{bmatrix} \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 2 & \cdots & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & \cdots & n \end{bmatrix} = \begin{bmatrix} b_{11} & 2b_{12} & \cdots & nb_{1n} \\ b_{21} & 2b_{22} & \cdots & nb_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & 2b_{n2} & \cdots & nb_{nn} \end{bmatrix}$$

By the equality of matrix, we have

$$ib_{ij} = jb_{ij} \text{ when } i \neq j.$$

Thus $b_{ij} = 0$ when $i \neq j$. This shows that all the matrices that are exchangeable with A are

diagonal matrices. For the set of diagonal matrices $C(A)$,

$$\begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix} \text{ is a basis of } C(A). \text{ Thus its}$$

dimension is n.

2. Please find a basis and the dimension of the solution space of the following system of linear equations

$$\begin{cases} 3x_1 + 2x_2 - 5x_3 + 4x_4 = 0 \\ 3x_1 - x_2 + 3x_3 - 3x_4 = 0 \\ 3x_1 + 5x_2 - 13x_3 + 11x_4 = 0 \end{cases}$$

Answer:

Transforming the system of linear equations into a matrix form, we have

$$\begin{bmatrix} 3 & 2 & -5 & 4 \\ 3 & -1 & 3 & -3 \\ 3 & 5 & -13 & 11 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Applying the elementary row operations, we can obtain the Reduced Row Echelon Form,

$$\begin{bmatrix} 1 & 0 & 1/9 & -2/9 \\ 0 & 1 & -8/3 & 7/3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = 0$$

This means

$$x_1 = -\frac{1}{9}x_3 + \frac{2}{9}x_4$$

$$x_2 = \frac{8}{3}x_3 - \frac{7}{3}x_4$$

$$x_3 = x_3$$

$$x_4 = x_4$$

Therefore, all the solution can be presented as following

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_3 \begin{bmatrix} -\frac{1}{9} \\ 8/3 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 2/9 \\ -7/3 \\ 0 \\ 1 \end{bmatrix}$$

and a basis of solution space is $\begin{bmatrix} -\frac{1}{9} \\ 8/3 \\ 1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 2/9 \\ -7/3 \\ 0 \\ 1 \end{bmatrix}$ and the dimension is 2.

Homework

1. Let $X = \{x | (x_1, x_2) \in \mathbf{R}^2\}$, for two fixed c_1, c_2 , let $f(x) = c_1x_1 + c_2x_2$, please show that $f(x)$ is a linear function defined on linear space X . Please show that set $X' = \{f(x) | f(x) = c_1x_1 + c_2x_2, c_1 \in \mathbf{R}, c_2 \in \mathbf{R}\}$ is a linear space and point out a basis of this space.

Proof: First we prove that $f(x)$ is a linear function.

For any $x = (x_1, x_2), y = (y_1, y_2) \in \mathbf{R}^2$, $x + y = (x_1 + y_1, x_2 + y_2), kx = (kx_1, kx_2)$

$$f(x + y) = c_1(x_1 + y_1) + c_2(x_2 + y_2) = c_1x_1 + c_2x_2 + c_1y_1 + c_2y_2 = f(x) + f(y)$$

$$f(kx) = c_1(kx_1) + c_2(kx_2) = k(c_1x_1 + c_2x_2) = kf(x)$$

Thus $f(x)$ is a linear function on linear space X .

Second, we prove that X' is a linear space, where the addition and scalar multiplication are the addition and scalar multiplication of real-valued functions.

For any $f(x) = f_1x_1 + f_2x_2, g(x) = g_1x_1 + g_2x_2 \in X', f_1, f_2 \in \mathbf{R}, g_1, g_2 \in \mathbf{R}$,

$$f(x) + g(x) = f_1x_1 + f_2x_2 + g_1x_1 + g_2x_2 = (f_1 + g_1)x_1 + (f_2 + g_2)x_2 \in X'$$

$$kf(x) = kf_1x_1 + kf_2x_2 = (kf_1)x_1 + (kf_2)x_2 \in X'$$

Thus the set is closed under addition and scalar multiplication. Next we prove the eight axioms:

$$1. f(x) + g(x) = f_1x_1 + f_2x_2 + g_1x_1 + g_2x_2 = g_1x_1 + g_2x_2 + f_1x_1 + f_2x_2 = g(x) + f(x)$$

$$\begin{aligned} 2. f(x) + (g(x) + h(x)) &= f_1x_1 + f_2x_2 + (g_1x_1 + g_2x_2 + h_1x_1 + h_2x_2) \\ &= (f_1x_1 + f_2x_2 + g_1x_1 + g_2x_2) + h_1x_1 + h_2x_2 \\ &= (f(x) + g(x)) + h(x) \end{aligned}$$

$$3. f(x) + 0(x) = f(x), \text{ where } 0(x) = 0x_1 + 0x_2 \text{ is the zero element.}$$

$$4. f(x) + (-f(x)) = 0, \text{ where } -f(x) = -f_1x_1 - f_2x_2$$

$$5. k(lf(x)) = k(lc_1x_1 + lc_2x_2) = (kl)(c_1x_1 + c_2x_2) = (kl)f(x)$$

$$\begin{aligned} 6. k(f(x) + g(x)) &= k(f_1x_1 + f_2x_2 + g_1x_1 + g_2x_2) = kf_1x_1 + kf_2x_2 + kg_1x_1 + kg_2x_2 \\ &= k(f_1x_1 + f_2x_2) + k(g_1x_1 + g_2x_2) = kf(x) + kg(x) \end{aligned}$$

7. $(k+l)f(x) = (k+l)(f_1x_1 + f_2x_2) = kf(x) + lf(x)$

8. $1f(x) = f(x)$

2. Let $X = \{h(s) \mid h(s) \text{ is a continuous function defined on } [0,1], 0 \leq s \leq 1\}$, for any point s_1 in $[0,1]$, please show that $f(h) = h(s_1)$ is a linear function defined on linear space X .

Proof: For any $h(s), g(s) \in X$,

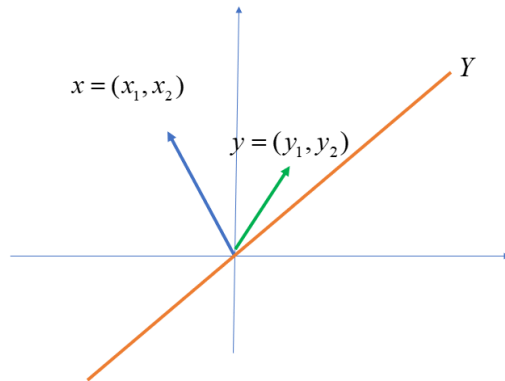
$$f(h(s) + g(s)) = h(s_1) + g(s_1) = f(h(s)) + f(g(s))$$

$$f(kh(s)) = kh(s_1) = kf(h(s))$$

Thus $f(h) = h(s_1)$ is a linear function.

Homework of quotient space

Let $X = \{x \mid x = (x_1, x_2) \in \mathbb{R}^2\}$. The vector x, y in X can be drawn as a vector in the following figure. Y is a line through the origin as described in the figure. Then Y is a subspace. Please draw the congruence class mod Y of x and y and draw the sum of two congruence classes $\{x\} + \{y\}$.



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Answer:

