

## HOMWORK 1

5 points

### 1. GAUSSIAN RV: UNCORRELATEDNESS IMPLIES INDEPENDENCE

Show that if two random variables  $X$  and  $Y$  are jointly normal and are uncorrelated, then they are independent.

Hint: Two random variables  $X, Y$  are jointly normal if

$$\text{pdf}(X, Y) = f_{X,Y}(x, y) = \frac{1}{2\pi |\det(C_Z)|^{1/2}} \exp \left[ -\frac{1}{2} (Z - E(Z))^T C_Z^{-1} (Z - E(Z)) \right],$$

in which  $Z = [X, Y]^T$ .

*Proof.* As  $X$  and  $Y$  are uncorrelated, then we have

$$\text{cov}(X, Y) = 0.$$

The covariance matrix  $C_z$  can then be written as,

$$C_z = \begin{bmatrix} \sigma_x^2 & 0 \\ 0 & \sigma_y^2 \end{bmatrix}$$

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Then the joint pdf of  $X, Y$  is,

$$f(x, y) = \frac{1}{2\pi\sigma_x\sigma_y} \exp \left[ -\frac{(x - EX)^2}{2\sigma_x^2} - \frac{(y - EY)^2}{2\sigma_y^2} \right] \quad |$$

and we can obtain the marginal distribution as follows,

$$f_X(x) = \frac{1}{\sqrt{2\pi}\sigma_x} e^{-\frac{(x-EX)^2}{2\sigma_x^2}}, \quad f_Y(y) = \frac{1}{\sqrt{2\pi}\sigma_y} e^{-\frac{(y-EY)^2}{2\sigma_y^2}} \quad |$$

□

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### 2. WIDE-SENSE STATIONARY

Consider the signal plus noise  $\mathbf{z}(n) = \mathbf{s} + \mathbf{v}(n)$ , where  $\mathbf{s}$  is a RV with  $E[\mathbf{s}] = 1$ ,  $E[\mathbf{s}^2] = 2$ , and for each value of  $n$ ,  $\mathbf{v}(n) \sim \mathcal{N}(0, 1)$ . It is known that  $E[\mathbf{s}\mathbf{v}(i)] = 1$  for all  $i$ , and  $\mathbf{v}(i)$  is independent of  $\mathbf{v}(j)$  for all  $i \neq j$ .

- (1) Compute the autocorrelation function  $R_z(i, j)$  of  $\mathbf{z}(n)$  for all integers  $i, j$ .
- (2) Is  $\mathbf{z}(n)$  WSS (Wide sense stationary)? If so, derive a mathematical expression for  $R_z(k)$ .

- Solution:

$$R_z(i, j) = E[\mathbf{z}(i)\mathbf{z}(j)] = E[(\mathbf{s} + \mathbf{v}(i))(\mathbf{s} + \mathbf{v}(j))] = \begin{cases} 4 & i \neq j \\ 5 & i = j \end{cases} \quad 2$$

Yes,  $\mathbf{z}(n)$  is wide sense stationary, which is because

$$E[\mathbf{z}(n)] = 1 \quad /$$

and

$$R_z(k) = \begin{cases} 4 & k \neq 0 \\ 5 & k = 0 \end{cases} \quad 2$$