

The Answer to Homework

1. Convex set

(1) Show that a polyhedron $\{x \in \mathbb{R}^n : Ax \leq b\}$ for some $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$, is convex.

Proof: Suppose $x_1, x_2 \in \{x \in \mathbb{R}^n : Ax \leq b\}$ and $\theta \in [0, 1]$.

Since $A(\theta x_1 + (1-\theta)x_2) = \theta Ax_1 + (1-\theta)Ax_2 \leq \theta b + (1-\theta)b = b$,

$$\theta x_1 + (1-\theta)x_2 \in \{x \in \mathbb{R}^n : Ax \leq b\}$$

Thus a polyhedron $\{x \in \mathbb{R}^n : Ax \leq b\}$ for some $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$, is convex.

(2) Consider a convex function $f : \mathbb{R}^n \rightarrow \mathbb{R}$. Prove that the set

$$\{(x, t) \mid f(x) \leq t, x \in \mathbb{R}^n, t \in \mathbb{R}\}$$

is convex.

Proof: Suppose $(x_1, t_1), (x_2, t_2) \in \{(x, t) \mid f(x) \leq t, x \in \mathbb{R}^n, t \in \mathbb{R}\}$ and $\theta \in [0, 1]$.

Since $f(\theta x_1 + (1-\theta)x_2) \leq \theta f(x_1) + (1-\theta)f(x_2) \leq \theta t_1 + (1-\theta)t_2$,

$$[\theta x_1 + (1-\theta)x_2, \theta t_1 + (1-\theta)t_2] \in \{(x, t) \mid f(x) \leq t, x \in \mathbb{R}^n, t \in \mathbb{R}\}.$$

Thus $\{(x, t) \mid f(x) \leq t, x \in \mathbb{R}^n, t \in \mathbb{R}\}$ is convex.

(3) Show that $\{x \in \mathbb{R}_+^n \mid \prod_{i=1}^n x_i \geq 1\}$ is convex. (Hint: If $a, b \geq 0$ and $0 \leq \theta \leq 1$, then

$$a^\theta b^{(1-\theta)} \leq \theta a + (1-\theta)b$$

Proof: Suppose $p, q \in \{x \in \mathbb{R}_+^n \mid \prod_{i=1}^n x_i \geq 1\}$ and $\theta \in [0, 1]$.

Since $\prod_{i=1}^n [\theta p_i + (1-\theta)q_i] \geq \prod_{i=1}^n p_i^\theta q_i^{1-\theta} = (\prod_{i=1}^n p_i)^\theta (\prod_{i=1}^n q_i)^{1-\theta} \geq 1$.

$$\theta p + (1-\theta)q \in \{x \in \mathbb{R}_+^n \mid \prod_{i=1}^n x_i \geq 1\}.$$

Thus $\{x \in \mathbb{R}_+^n \mid \prod_{i=1}^n x_i \geq 1\}$ is convex.

(4) Show that the set $\{x \mid \|x-a\|_2 \leq \theta \|x-b\|_2\}$, where $a \neq b$ and $0 \leq \theta \leq 1$, is convex.

$$\begin{aligned}
\text{Proof: } \{x \mid \|x-a\|_2 \leq \theta \|x-b\|_2\} &= \{x \mid \|x-a\|_2^2 \leq \theta \|x-b\|_2^2\} \\
&= \{x \mid (x-a)^T(x-a) \leq \theta(x-b)^T(x-b)\} \\
&= \{x \mid (1-\theta)x^T x + (2\theta b^T - 2a^T)x + a^T a - \theta b^T b \leq 0\}
\end{aligned}$$

Since $0 \leq \theta \leq 1$, the Hessian matrix of function

$$f(x) = (1-\theta)x^T x + (2\theta b^T - 2a^T)x + a^T a - \theta b^T b$$

is $(1-\theta)I$ is a positive semidefinite matrix. Thus, the function $f(x)$ is a convex function, the 0-sublevel set is convex.

2. Convex function

(1) Prove that the entropy function, defined as

$$f(x) = -\sum_{i=1}^n x_i \log(x_i)$$

with $\text{dom}(f) = \{x \in \mathbf{R}_{++}^n : \sum_{i=1}^n x_i = 1\}$, is strictly concave.

Proof:

$$\begin{aligned}
\nabla f &= [-(\log x_1 + 1) \quad -(\log x_2 + 1) \quad \cdots \quad -(\log x_n + 1)] \\
\nabla^2 f &= \begin{bmatrix} -\frac{1}{x_1} & 0 & \cdots & 0 \\ 0 & -\frac{1}{x_2} & \cdots & 0 \\ 0 & 0 & \ddots & 0 \\ 0 & 0 & \cdots & -\frac{1}{x_n} \end{bmatrix}
\end{aligned}$$

Which is a negative matrix since $x \in \mathbf{R}_{++}^n$.

Moreover, the set $\text{dom}(f) = \{x \in \mathbf{R}_{++}^n : \sum_{i=1}^n x_i = 1\}$ is a convex set. Thus, the entropy function, defined as

$$f(x) = -\sum_{i=1}^n x_i \log(x_i)$$

with $\text{dom}(f) = \{x \in \mathbf{R}_{++}^n : \sum_{i=1}^n x_i = 1\}$, is strictly concave.

(2) Show that $f(x_1, x_2) = \frac{1}{x_1 x_2}$ on \mathbf{R}_{++}^2 is convex.

Proof: $\nabla f = \begin{bmatrix} -\frac{1}{x_1^2 x_2} & -\frac{1}{x_1 x_2^2} \end{bmatrix}$

$\nabla^2 f = \begin{bmatrix} \frac{2}{x_1^3 x_2} & \frac{1}{x_1^2 x_2^2} \\ \frac{1}{x_1^2 x_2^2} & \frac{2}{x_1 x_2^3} \end{bmatrix}$, since $x \in \mathbf{R}_{++}^2$, matrix $\nabla^2 f$ is a positive semidefinite matrix.

The domain \mathbf{R}_{++}^2 is a convex set. Therefore, the function $f(x_1, x_2) = \frac{1}{x_1 x_2}$ on \mathbf{R}_{++}^2 is convex.

(3) Show that $f(X) = \text{tr}(X^{-1})$ is convex on $\text{dom } f = \mathbf{S}_{++}^n$

Proof:

Define $g(t) = f(Z + tV)$ where $Z \in \mathbf{S}_{++}^n, V \in \mathbf{S}^n$

$$g(t) = \text{tr}[(Z + tV)^{-1}] = \text{tr}[Z^{-1}(I + tZ^{-\frac{1}{2}}VZ^{-\frac{1}{2}})^{-1}]$$

$$= \text{tr}[Z^{-1}Q(I + t\Lambda)^{-1}Q^T]$$

where $Z^{-\frac{1}{2}}VZ^{-\frac{1}{2}} = Q^T \Lambda Q$, $\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$

Thus $g(t) = \text{tr}[Z^{-1}Q(I + t\Lambda)^{-1}Q^T] = \text{tr}[Q^T Z^{-1}Q(I + t\Lambda)^{-1}] = \sum_{i=1}^n (Q^T Z^{-1}Q)_{ii} (1 + t\lambda_i)^{-1}$

Function $g(t)$ is a positive weighted sum of convex function $\frac{1}{1 + t\lambda_i}$. Therefore $g(t)$ is

convex. The set $\text{dom } f = \mathbf{S}_{++}^n$ is a convex set. Thus function $f(X) = \text{tr}(X^{-1})$ is convex on

$\text{dom } f = \mathbf{S}_{++}^n$.

3. Dual problem

(1) Formulate the dual problems of the following problems with one inequality constraint

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & f(x) \leq 0 \end{aligned}$$

Answer: For $\lambda = 0$, $g(\lambda) = \inf_x c^T x = -\infty$

For $\lambda > 0$, $g(\lambda) = \inf_x [c^T x + \lambda f(x)] = \lambda \inf_x [(\frac{c}{\lambda})^T x + f(x)]$

$$= -\lambda \sup_x [-(\frac{c}{\lambda})^T x - f(x)] = -\lambda f^*(\frac{c}{\lambda})$$

Thus, the dual problem is

$$\begin{aligned} \max \quad & -\lambda f^*(\frac{c}{\lambda}) \\ \text{s.t.} \quad & \lambda > 0 \end{aligned}$$

(2) Find the dual problem of the following general Linear programming

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & Gx \leq h \\ & Ax = b \end{aligned}$$

Answer:

The Lagrangian function is

$$\begin{aligned} l(x, \lambda, v) &= c^T x + \lambda^T (Gx - h) + v^T (Ax - b) \\ &= (c + G^T \lambda + A^T v)^T x - \lambda^T h + v^T b \end{aligned}$$

The dual function is

$$g(\lambda, v) = \inf_x L(x, \lambda, v) = \begin{cases} -\lambda^T h - v^T b, & c + G^T \lambda + A^T v = 0 \\ -\infty, & \text{otherwise} \end{cases}$$

Thus the dual problem is

$$\begin{aligned} \max_{\lambda, v} \quad & -h^T \lambda - b^T v \\ \text{s.t.} \quad & \lambda \geq 0 \\ & c + G^T \lambda + A^T v = 0 \end{aligned}$$

4. KKT condition

(1) Give the KKT conditions of the following optimization problem

$$\begin{aligned} \min \quad & x_1^2 + x_2^2 \\ \text{s.t.} \quad & (x_1 - 1)^2 + (x_2 - 1)^2 \leq 1 \\ & (x_1 - 1)^2 + (x_2 + 1)^2 \leq 1 \end{aligned}$$

Answer:

The KKT conditions are

$$\begin{aligned}
(x_1 - 1)^2 + (x_2 - 1)^2 &\leq 1 \\
(x_1 - 1)^2 + (x_2 + 1)^2 &\leq 1 \\
\lambda_1 &\geq 0, \quad \lambda_2 \geq 0 \\
\lambda_1[(x_1 - 1)^2 + (x_2 - 1)^2 - 1] &= 0 \\
\lambda_2[(x_1 - 1)^2 + (x_2 + 1)^2 - 1] &= 0 \\
x_1 + \lambda_1(x_1 - 1) + \lambda_2(x_1 - 1) &= 0 \\
x_2 + \lambda_1(x_2 - 1) + \lambda_2(x_2 + 1) &= 0
\end{aligned}$$

(2) Consider the equality constrained least square problem

$$\begin{aligned}
\min \quad & \|Ax - b\|_2^2 \\
\text{s.t.} \quad & Gx = h
\end{aligned}$$

Where $A \in \mathbb{R}^{m \times n}$ with $\text{rank}A = n$ and $G \in \mathbb{R}^{p \times n}$ with $\text{rank}G = p$

Give the KKT conditions and derive expressions for the primal solution x^* and the dual solution v^* .

Answer:

The KKT conditions is

$$\begin{aligned}
Gx &= h \\
2A^T Ax &= 2A^T b - G^T v
\end{aligned}$$

We can solve the linear equation to obtain the optimal solution

First, since $\text{rank}A = n$, $A^T A$ is invertible, we may obtain

$$x = \frac{1}{2}(A^T A)^{-1}(2A^T b - G^T v) \quad (*)$$

Putting it into the first equation, we have

$$\begin{aligned}
G\left[\frac{1}{2}(A^T A)^{-1}(2A^T b - G^T v)\right] &= h \\
\frac{1}{2}G(A^T A)^{-1}G^T v &= G(A^T A)^{-1}A^T b - h
\end{aligned}$$

Thus the optimal solution of dual problem $v^* = 2[G(A^T A)^{-1}G^T]^{-1}[G(A^T A)^{-1}A^T b - h]$

Putting it into (*), we obtain the optimal solution for the primal solution

$$x^* = (A^T A)^{-1}\{A^T b - G^T [G(A^T A)^{-1}G^T]^{-1}[G(A^T A)^{-1}A^T b - h]\}$$

5. Gradient and Newton Descent

Consider the optimization

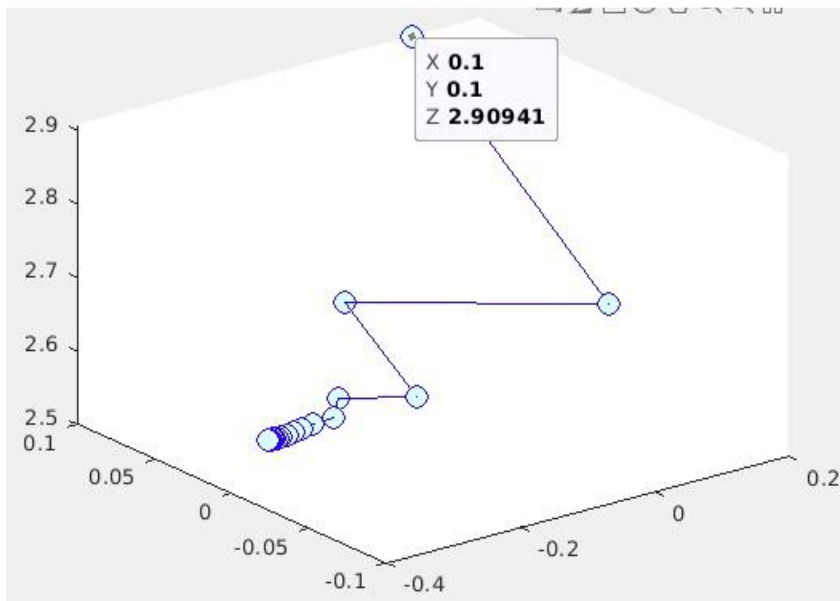
$$\min_{x_1, x_2} e^{x_1+3x_2-0.1} + e^{x_1-3x_2-0.1} + e^{-x_1-0.1}$$

Write a code to solve this optimization using the gradient method and Newton method with the backtracking parameters $\alpha=0.1$ and $\beta=0.6$, draw $f(x_k)$ verses k for k =0, 1, 2.....,50.

```

1 Alpha = 0.1;
2 Beta = 0.6;
3 nK = 50;
4 x0 = [0.1;0.1];
5
6 points = zeros(3,nK);
7 x = x0;
8 for iter = 1:nK
9     val = exp(x(1)+3*x(2)-0.1)+exp(x(1)-3*x(2)-0.1)+exp(-x(1)-0.1);
10    grad = [exp(x(1)+3*x(2)-0.1)+exp(x(1)-3*x(2)-0.1)-exp(-x(1)-0.1);
11           3*exp(x(1)+3*x(2)-0.1)-3*exp(x(1)-3*x(2)-0.1)];
12    points(1,iter)=x(1);
13    points(2,iter)=x(2);
14    points(3,iter)=val;
15    v = -grad;
16    x = x+Alpha*v;
17 end
18 plot3(points(1,:),points(2,:),points(3,:), '-o', 'Color', 'b', 'MarkerSize', 10, ...
19       'MarkerFaceColor', '#D9FFFF')

```



```

1 Alpha = 0.1;
2 Beta = 0.6;
3 nK = 50;
4 x0 = [0.1;0.1];
5
6 points = zeros(3,nK);
7 x = x0;
8 for iter = 1:nK
9     val = exp(x(1)+3*x(2)-0.1)+exp(x(1)-3*x(2)-0.1)+exp(-x(1)-0.1);
10    grad = [exp(x(1)+3*x(2)-0.1)+exp(x(1)-3*x(2)-0.1)-exp(-x(1)-0.1);
11           3*exp(x(1)+3*x(2)-0.1)-3*exp(x(1)-3*x(2)-0.1)];
12    hess = [exp(x(1)+3*x(2)-0.1)+exp(x(1)-3*x(2)-0.1)+exp(-x(1)-0.1), 3*exp(x(1)+3*x(2)-0.1)-3*exp(x(1)-3*x(2)-0.1);
13           3*exp(x(1)+3*x(2)-0.1)-3*exp(x(1)-3*x(2)-0.1), 9*exp(x(1)+3*x(2)-0.1)+9*exp(x(1)-3*x(2)-0.1)];
14    points(1,iter)=x(1);
15    points(2,iter)=x(2);
16    points(3,iter)=val;
17    v = -hess\grad;
18    x = x+Alpha*v;
19 end
20 plot3(points(1,:),points(2,:),points(3,:), '-o', 'Color', 'b', 'MarkerSize', 10, ...
21       'MarkerFaceColor', '#D9FFFF')

```

