

Signature  
from  
Head of  
the School

Harbin Institute of Technology, Shenzhen

Fall Semester of 2024

# Convex Optimization and Optimal Control

## Examination (A)

Question	One	Two	Three	Four	Five	Six	Seven	Eight	Nine	Ten	Total
Mark											

P.S.: This paper was memorized and typeset after the examination ended, and there's no cheating behaviour during the examination.

DEPARTMENT: \_\_\_\_\_ CLASS: \_\_\_\_\_ STUDENT ID: \_\_\_\_\_ NAME: \_\_\_\_\_

密  
封  
线

1. (16 Points) Prove that the following two sets are convex sets. (8 points each)

(1)  $\{a = (a_0, a_1, \dots, a_{k-1}) \in R^k \mid p(0) = 1, |p(t)| \leq 1, p(t) = a_0 + a_1 t + \dots + a_{k-1} t^{k-1}\}$

(2)  $\{(x, y, z) \mid z \geq x^2 + y^2\} \subset R^3$

---

2. (16 Points) Prove that the following two functions are convex (or concave). (8 points each)

(1) The perspective of a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is the function  $g : \mathbb{R}^n \times \mathbb{R} \rightarrow \mathbb{R}$

$$g(x, t) = tf(x/t), \quad \text{dom } g = \{(x, t) \mid x/t \in \text{dom } f, t > 0\}$$

Prove that  $g$  is convex if  $f$  is convex.

(2)  $L(x, \lambda, \nu) = \inf_{x \in D} \left( \sum_{i=1}^m \lambda_i x_i + \sum_{i=1}^m \nu_i x_i^2 \right), \lambda, \nu \in \mathbb{R}^m$

DEPARTMENT: \_\_\_\_\_ CLASS: \_\_\_\_\_ STUDENT ID: \_\_\_\_\_ NAME: \_\_\_\_\_

.....  
密  
.....  
封  
.....  
线  
.....

3. (10 Points) Formulate the following problem into a convex optimization problem:

$$\begin{aligned} \min & \|x\|_1 \\ \text{s.t.} & Ax = b \end{aligned}$$

---

4. (10 Points) Formulate the KKT conditions for the following convex optimization problem:

$$\begin{aligned} \min & \frac{1}{2} x^T P x + q^T x + r \\ \text{s.t.} & Ax = b \end{aligned}$$

DEPARTMENT: \_\_\_\_\_ CLASS: \_\_\_\_\_ STUDENT ID: \_\_\_\_\_ NAME: \_\_\_\_\_

密  
封  
线

5. (20 Points) Formulate the dual problems for the following convex optimization problems. (10 points each)

(1)

$$\begin{aligned} \min x^T x \\ \text{s.t. } Ax = b \end{aligned}$$

(2)

$$\begin{aligned} \min c^T x \\ \text{s.t. } Ax = b \\ x \geq 0 \end{aligned}$$

---

6. (15 Points) Suppose the state equations of the system is

$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = u \end{cases}$$

The initial conditions are

$$\begin{cases} x_1(0) = 1 \\ x_2(0) = 1 \end{cases}$$

and the terminal conditions are

$$\begin{cases} x_1(1) = 0 \\ x_2(1) \text{ is free} \end{cases}$$

Derive the optimal control rule to minimize

$$J(u) = \int_0^1 u^2(t) dt .$$

DEPARTMENT: \_\_\_\_\_ CLASS: \_\_\_\_\_ STUDENT ID: \_\_\_\_\_ NAME: \_\_\_\_\_

密  
封  
线

7. (13 Points) Formulate the following robust linear program problem into convex optimization problem.

$$\min c^T x$$

$$\text{s.t. } a_i^T x \leq b_i, \text{ where } a_i \in \mathcal{E}_i = \{\bar{a}_i + P_i u \mid \|u\|_2 \leq 1\}, \bar{a}_i \in R^n, P_i \in R^{n \times n}$$

$$i = 1, \dots, n$$