

第一章: n 阶行列式

① 一个定义 $D = \Delta(a_{ij}) = \sum_{p_1 \dots p_n} (-1)^{t(p_1 \dots p_n)} a_{1p_1} + \dots + a_{np_n}$
 $= \sum_{q_1 \dots q_n} (-1)^{t(q_1 \dots q_n)} a_{q_1 1} + \dots + a_{q_n n}$

② 五个性质 n 阶行列式
 $D' = D$ (转置为自身)

$D \xrightarrow{r_i \rightarrow r_j} D = D$
2) 提出因子 ($\frac{D}{k}, k \neq 0$) $\tilde{D} = \frac{D}{k}$
3) $r_i + kr_j$ $\tilde{D} = D$
部分可加性

} 计算行列式

$D: R^{n^2} \rightarrow R$ $n \times n$ 数表 \rightarrow 数

③ 展开定理 $D = \sum_k a_{ik} A_{ik}$

错位展开为0

④ 克莱姆法则

例1.
$$\begin{vmatrix} x+a & a & \dots & a \\ a & x+a & \dots & a \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \dots & x+a \end{vmatrix}$$

法①. 原式 $C_i + C_j \ (i=2 \dots n)$

$$(x+na) \begin{vmatrix} 1 & a & \dots & a \\ 1 & x-a & \dots & a \\ \vdots & \vdots & \ddots & \vdots \\ 1 & a & \dots & x-a \end{vmatrix}$$

$$\underline{C_i - aC_j} \begin{vmatrix} 1 & 0 & \dots & 0 \\ 1 & x & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 0 & \dots & x \end{vmatrix}$$

法② $r_i - r_n$

$$i=n-1$$

$$\begin{vmatrix} x & 0 & \dots & -x \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & x-x \\ a & a & \dots & a \end{vmatrix} \begin{matrix} \\ \\ \\ \rightarrow \text{展开} \end{matrix}$$

↓
公式

法③

$$\begin{vmatrix} x+a & a & \dots & a \\ a & x+a & \dots & a \\ \vdots & \vdots & \ddots & \vdots \\ a & a & \dots & x+a \end{vmatrix}$$

\Leftrightarrow

$$\begin{vmatrix} x+a & a & \dots & a & 0 \\ a & x+a & \dots & a & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a & a & \dots & x+a & 0 \\ a & a & \dots & a & 1 \end{vmatrix}$$

$$f(x) = a_0 + a_1 x + a_2 x^2$$

$$\begin{cases} x_1 \rightarrow f(x_1) = f_1 \\ x_2 \rightarrow f(x_2) = f_2 \\ x_3 \rightarrow f(x_3) = f_3 \end{cases}$$

$$= \begin{vmatrix} x & 0 & \dots & 0 & 1 \\ 0 & x & \dots & 0 & -1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & x & -1 \\ a & a & \dots & a & 1 \end{vmatrix} = \dots$$

Vander monde 行列式

$$\begin{cases} a_0 + a_1 x_1 + a_2 x_1^2 = f_1 \\ a_0 + a_1 x_2 + a_2 x_2^2 = f_2 \\ a_0 + a_1 x_3 + a_2 x_3^2 = f_3 \end{cases}$$

$$D_n = \begin{vmatrix} 1 & 1 & \dots & 1 \\ x_1 & x_2 & \dots & x_n \\ \vdots & \vdots & \ddots & \vdots \\ x_1^{n-2} & x_2^{n-2} & \dots & x_n^{n-2} \\ x_1^{n-1} & x_2^{n-1} & \dots & x_n^{n-1} \end{vmatrix}$$

←

$$D = \begin{vmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \end{vmatrix}$$

辗转相除法

$$= \begin{vmatrix} 1 & & & & \\ x_1 - x_1 & & & & \\ & 1 & & & \\ & x_2 - x_1 & & & \\ & & \ddots & & \\ & & & 1 & \\ & & & x_n - x_1 & \\ & & & & \ddots \\ x_1^{n-1} - x_1^{n-1} & x_2^{n-1} - x_1 x_2^{n-2} & \dots & x_n^{n-1} - x_1 x_n^{n-2} & \dots \end{vmatrix} = (x_2 - x_1) \dots (x_n - x_1) \begin{vmatrix} 1 & & & & \\ & 1 & & & \\ & & \ddots & & \\ & & & 1 & \\ & & & & \ddots \end{vmatrix}$$

例

$$\begin{vmatrix} 1 & 1 & 1 & \dots & 1 \\ x_1 & x_2 & x_3 & \dots & x_n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ x_1^{n-2} & x_2^{n-2} & x_3^{n-2} & \dots & x_n^{n-2} \\ x_1^n & x_2^n & x_3^n & \dots & x_n^n \end{vmatrix}$$

→ 构造 $D_{n+1} =$

$$\begin{vmatrix} 1 & 1 & 1 & \dots & 1 & 1 \\ x_1 & x_2 & x_3 & \dots & x_n & x \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ x_1^{n-2} & x_2^{n-2} & x_3^{n-2} & \dots & x_n^{n-2} & x^{n-2} \\ x_1^{n-1} & x_2^{n-1} & x_3^{n-1} & \dots & x_n^{n-1} & x^{n-1} \\ x_1^n & x_2^n & x_3^n & \dots & x_n^n & x^n \end{vmatrix}$$

$$= \underbrace{\left[\prod_{i>j} (x_i - x_j) \right]}_{\text{范}} (x - x_1) \dots (x - x_n)$$

范

$$\tilde{D}_{n+1}(x) = A_{1,n+1} + x A_{2,n+1} + \dots + x^n A_{n+1,n+1}$$

关于 x 的 n 次多项式

$A_{n,n+1}$ 是 x^n 的系数 $= (-1)^{2n+1} D_n$

$$D_n = -A_{n,n+1} = - \underbrace{[-x_1 - x_2 - \dots - x_n]}_{\substack{\text{---} \\ i>j}} \prod_{i>j} (x_i - x_j)$$

$$= \left(\sum_{k=1}^n x_k \right) \prod_{i>j} (x_i - x_j)$$

格式

$$D = \begin{vmatrix} 1 & & \\ & 1 & \\ & & \ddots \end{vmatrix} = \begin{vmatrix} 1 & & \\ & 1 & \\ & & \ddots \end{vmatrix} = ?$$

同理 $D_1 = \begin{vmatrix} 1 & \\ & 1 \end{vmatrix} = ?$

\dots
 $D_k \dots$

由克莱姆法则可得 $x_1 = \frac{D_1}{D} \dots$